

PRELIMINARY STUDY FOR A COMPUTATIONAL FLUID DYNAMICS ANALYSIS ON THE INFLUENCE OF VARIABLE CANT ANGLE WINGLETS ON TOTAL DRAG REDUCTION

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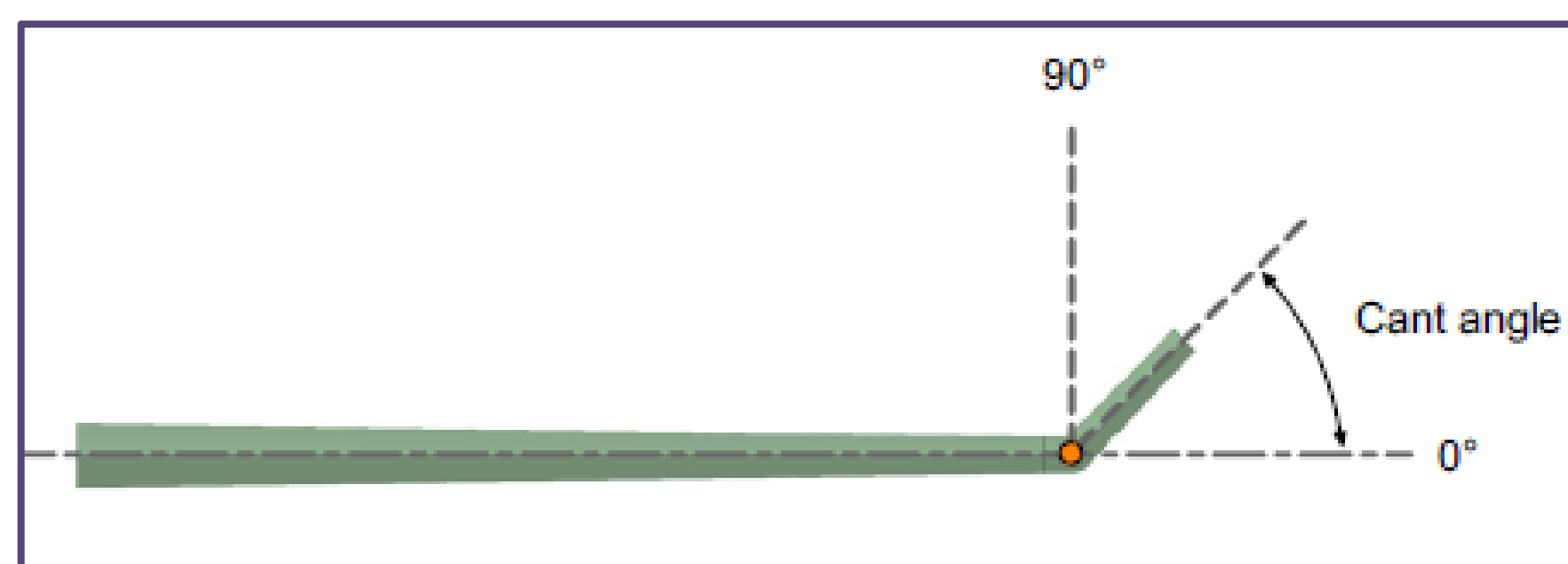
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INTRODUCTION

The development of wingtip devices has been motivated by the need to reduce lift-induced drag in aircraft. Traditional winglets, fixed devices attached at the tips of the wings, have limitations in terms of lift-induced drag reduction and their inability to adapt to changing flight conditions. To address this issue, this study proposes the use of **variable cant angle** winglets that can be adjusted to **optimize drag reduction** under different flight conditions.

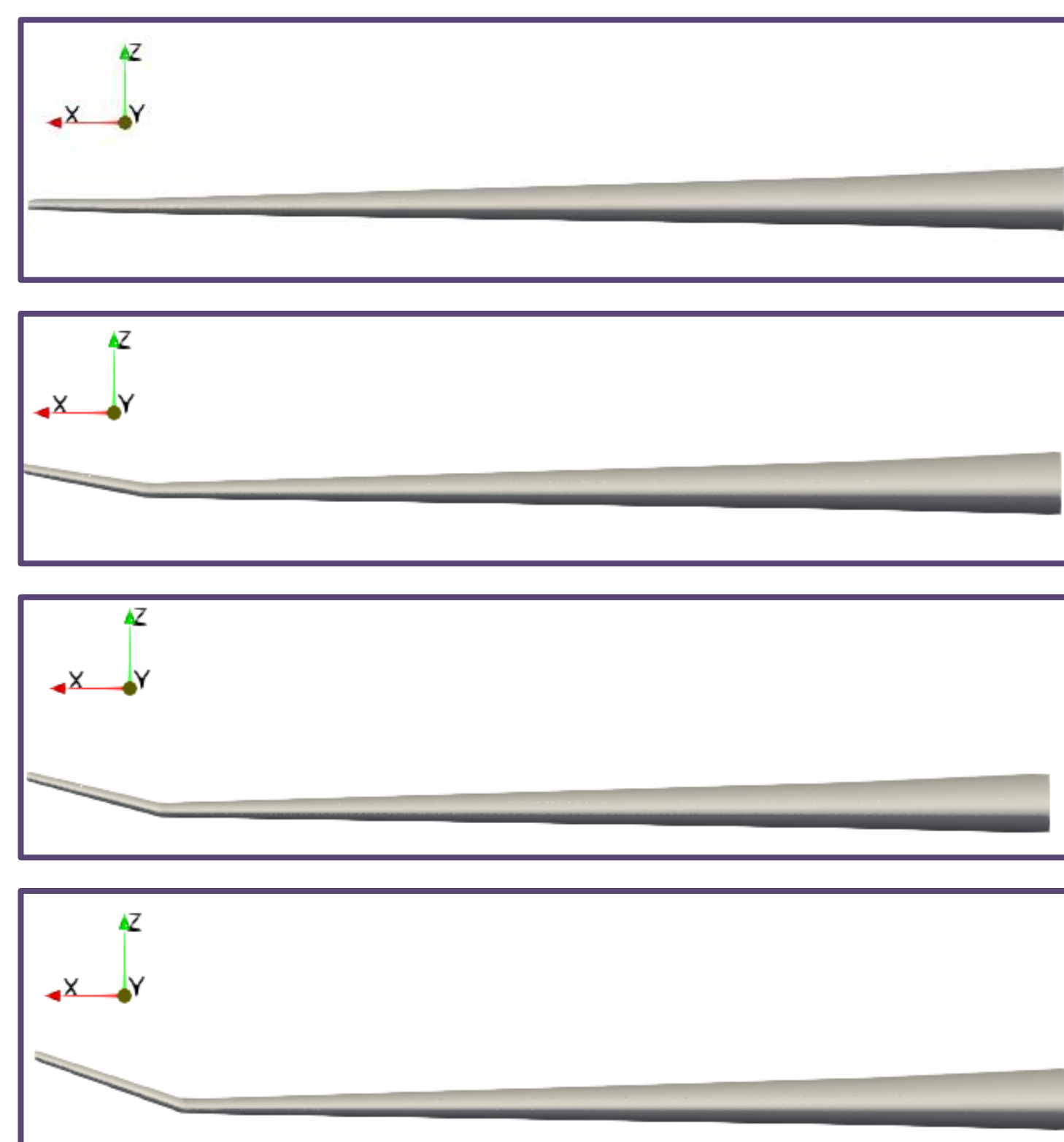
MORPHING APPROACH

The study employs computational fluid dynamics software, specifically OpenFOAM, to investigate the effects of varying the winglet cant angle modifying the wing geometry. An operator is used as a source to define the wing geometry. The solver is transient, allowing for the examination of **multiple winglet positions**.

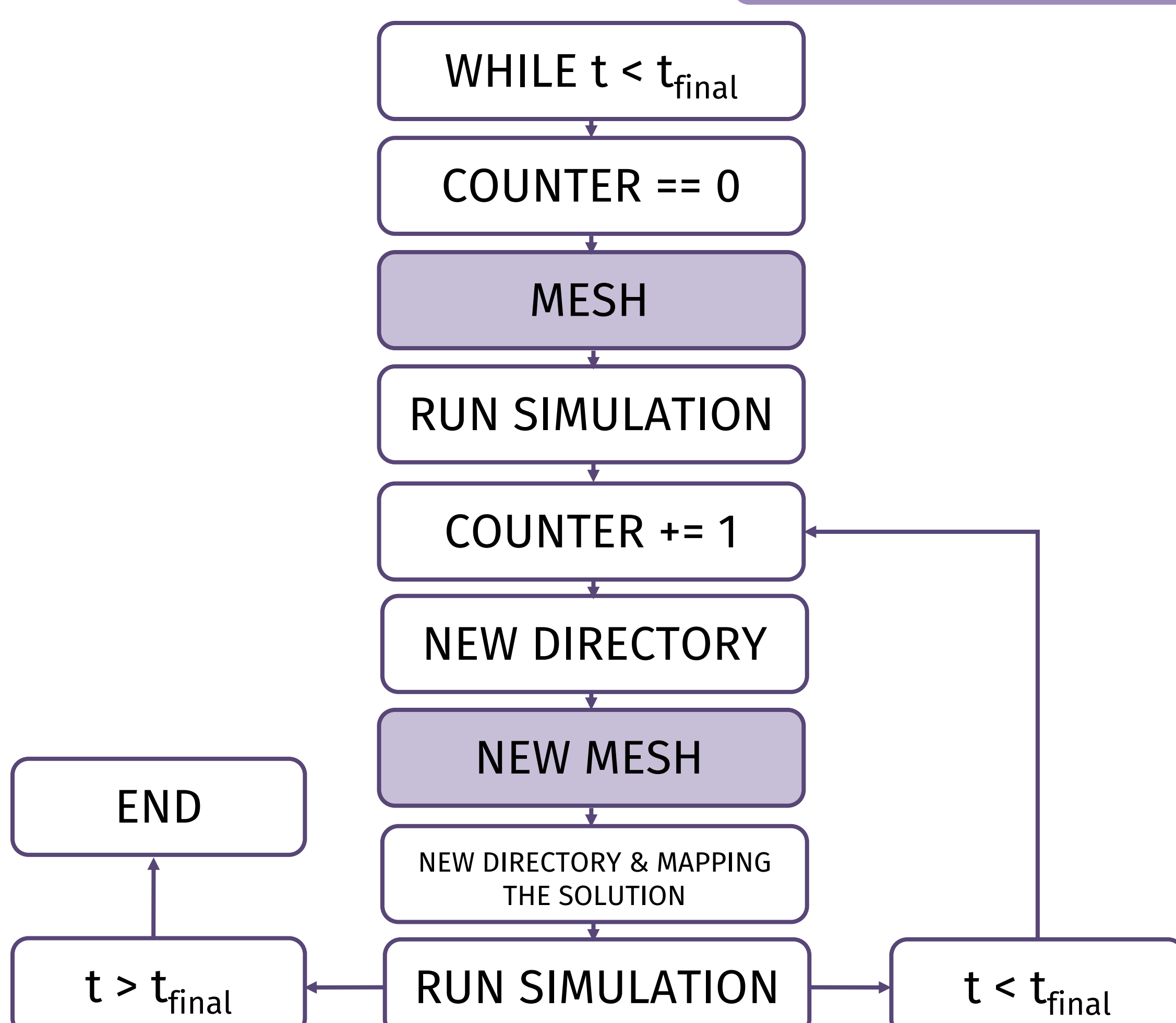


$$f_1(x, t) = \sin(\omega t) \cdot (x - x_0)$$

$$f_2(x, t) = \sin(\omega t) \cdot \frac{(x - x_0)}{1 + e^{-k(x-x_0)}}$$



(RE)MESHING APPROACH



```

while t < tFinal;
if counter == 0;
  print("-----> Remeshing iteration number: {counter}")
  # CREATE THE MESH - path = f/lapp@lnd_{counter}
  AllMesh = f"/f/lapp@lnd_{counter}/AllMesh"
  os.system(AllMesh)
  os.system("sed -i 's/minX/left/' {path}/constant/polyMesh/boundary")
  os.system("sed -i 's/maxX/right/' {path}/constant/polyMesh/boundary")
  os.system("sed -i 's/minY/outlet/' {path}/constant/polyMesh/boundary")
  os.system("sed -i 's/maxY/inlet/' {path}/constant/polyMesh/boundary")
  os.system("sed -i 's/minZ/bottom/' {path}/constant/polyMesh/boundary")
  os.system("sed -i 's/maxZ/top/' {path}/constant/polyMesh/boundary")
endif

# RUN THE SIMULATION
AllSolver = f"/{path}/AllSolver"
os.system(AllSolver)

# UPDATE THE COUNTER
counter += 1

# FROM THE PREVIOUS DIRECTORY, COPY IN A NEW DIRECTORY - NEW NAME
newDir = f"/cp -r f/lapp@lnd_{counter-1} f/lapp@lnd_{counter}"
os.system(newDir)

# EXTRACT THE GEOMETRY
goExtract = f"/surfaceMesh/triangulate -case f/lapp@lnd_{counter} -patches {wing} wing_{counter}.stl > f/lapp@lnd_{counter}/log_surfaceMeshTriangulate"
os.system(goExtract)
goMove = f"/mv f/lapp@lnd_{counter}/wing_{counter}.stl f/lapp@lnd_{counter}/constant/triSurface"
os.system(goMove)

# CHANGE THE NAME OF snappyHexMeshDict AND surfaceFeaturesDict
modSnappyHexMeshDict = f"sed -i 's/wing_{counter-1}/wing_{counter}/' f/lapp@lnd_{counter}/system/snappyHexMeshDict"
modSurfaceDict = f"sed -i 's/wing_{counter-1}/wing_{counter}/' f/lapp@lnd_{counter}/system/surfaceFeaturesDict"
os.system(modSnappyHexMeshDict)
os.system(modSurfaceDict)

# CREATE A NEW MESH
AllMesh = f"/f/lapp@lnd_{counter}/AllMesh"
os.system(AllMesh)
os.system("sed -i 's/minX/left/' f/lapp@lnd_{counter}/constant/polyMesh/boundary")
os.system("sed -i 's/maxX/right/' f/lapp@lnd_{counter}/constant/polyMesh/boundary")
os.system("sed -i 's/minY/outlet/' f/lapp@lnd_{counter}/constant/polyMesh/boundary")
os.system("sed -i 's/maxY/inlet/' f/lapp@lnd_{counter}/constant/polyMesh/boundary")
os.system("sed -i 's/minZ/bottom/' f/lapp@lnd_{counter}/constant/polyMesh/boundary")
os.system("sed -i 's/maxZ/top/' f/lapp@lnd_{counter}/constant/polyMesh/boundary")
endif

# CHECK THE END TIME FROM THE PREVIOUS MESH TIMESTEP
oldTime = f"/{path}/time -case f/lapp@lnd_{counter-1}
prevTimeStep = f"/{path}/time -case f/lapp@lnd_{counter-1} | tail -n 1"
newDirName = subprocess.check_output(prevTimeStep, shell=True).decode("utf-8")
newDirName = newDirName + ".old" if newDirName[-1] == "." else newDirName
os.system(f"mv {path}/time {path}/time_{newDirName}")

# MAPPING THE SOLUTION
mapping = f"/cd f/lapp@lnd_{counter} | mapFields -f f/lapp@lnd_{counter-1} -sourceTime {prevTimeStep} -mapMethod cellPointInterpolate -noFunctionObjects -constant"
os.system(mapping)

# CHECK THE END TIME FROM THE PREVIOUS CONTROLDict
oldTime_v = f"/{path}/dictionary -entry endTime -value f/lapp@lnd_{counter-1}/system/controlDict"
oldTime_v = subprocess.check_output(oldTime_v, shell=True)

# MODIFY THE CONTROLDict IN THE NEW DIRECTORY
newDirTime_v = round(float(oldTime_v), 6) + interval
newDirTime = f"/{path}/dictionary -entry endTime set {newDirTime_v} f/lapp@lnd_{counter-1}/system/controlDict"
os.system(newDirTime)
t = newDirTime_v

# RUN THE SIMULATION
AllSolver = f"/{path}/AllSolver"
os.system(AllSolver)

# UPDATE THE COUNTER
counter += 1
  
```